

# Optimal Control and Inverse Problems for PDEs. Inverse Stefan Problem - Part 3

Ugur G. Abdulla

Florida Institute of Technology

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**Inverse Stefan Problem (ISP):** Find the functions  $u(x, t)$  and  $s(t)$  and the boundary heat flux  $g(t)$  satisfying conditions

$$(a(x, t)u_x)_x + b(x, t)u_x + c(x, t)u - u_t = f(x, t), \quad \text{for } (x, t) \in \Omega$$

$$u(x, 0) = \phi(x), \quad 0 \leq x \leq s(0) = s_0$$

$$a(0, t)u_x(0, t) = g(t), \quad 0 \leq t \leq T$$

$$a(s(t), t)u_x(s(t), t) + \gamma(s(t), t)s'(t) = \chi(s(t), t), \quad 0 \leq t \leq T$$

$$u(s(t), t) = \mu(t), \quad 0 \leq t \leq T$$

$$u(0, t) = \nu(t), \quad \text{for } 0 \leq t \leq T$$

# Optimal Control Problem

$$\mathcal{J}(v) = \beta_0 \|u(0, t) - \nu(t)\|_{L_2[0, T]}^2 + \beta_1 \|u(s(t), t) - \mu(t)\|_{L_2[0, T]}^2 \quad (1)$$

$$V_R = \left\{ v = (s, g) \in W_2^2[0, T] \times W_2^1[0, T] : \delta \leq s(t) \leq l, \right. \\ \left. s(0) = s_0, \max(\|s\|_{W_2^2}; \|g\|_{W_2^1}) \leq R \right\}$$

$$(a(x, t)u_x)_x + b(x, t)u_x + c(x, t)u - u_t = f(x, t), \quad \text{for } (x, t) \in \Omega \quad (2)$$

$$u(x, 0) = \phi(x), \quad 0 \leq x \leq s(0) = s_0 \quad (3)$$

$$a(0, t)u_x(0, t) = g(t), \quad 0 \leq t \leq T \quad (4)$$

$$a(s(t), t)u_x(s(t), t) + \gamma(s(t), t)s'(t) = \chi(s(t), t), \quad 0 \leq t \leq T \quad (5)$$

$$\Omega = \{(x, t) : 0 < x < s(t), 0 < t \leq T\}$$

# Discrete Optimal Control Problem

$$\omega_\tau = \{t_j = j \cdot \tau, j = 0, 1, \dots, n\}$$

$$V_R^n = \{[v]_n = ([s]_n, [g]_n) \in \mathbb{R}^{2n+2} : 0 < \delta \leq s_k \leq l,$$

$$\max(\|[s]_n\|_{w_2}^2; \|[g]_n\|_{w_1}^2) \leq R^2\}$$

$$[s]_n = (s_0, s_1, \dots, s_n) \in \mathbb{R}^{n+1}, [g]_n = (g_0, g_1, \dots, g_n) \in \mathbb{R}^{n+1}$$

$$\|[s]_n\|_{w_2}^2 = \sum_{k=0}^{n-1} \tau s_k^2 + \sum_{k=1}^n \tau s_{\bar{t},k}^2 + \sum_{k=1}^{n-1} \tau s_{\bar{t}\bar{t},k}^2, \|[g]_n\|_{w_1}^2 = \sum_{k=0}^{n-1} \tau g_k^2 + \sum_{k=1}^n \tau g_{\bar{t},k}^2.$$

$$s_{\bar{t},k} = \frac{s_k - s_{k-1}}{\tau}, s_{t,k} = \frac{s_{k+1} - s_k}{\tau}, s_{\bar{t}\bar{t},k} = \frac{s_{k+1} - 2s_k + s_{k-1}}{\tau^2}.$$

## Definition 1

$[u([v]_n)]_n = (u(x; 0), u(x; 1), \dots, u(x; n))$  is called discrete state vector if

1.  $u(x; 0) = \phi(x) \in W_2^1[0, s_0]$ ;
2.  $u(x; k) \in W_2^1[0, s_k]$  satisfy the integral identity

$$\int_0^{s_k} \left( a_k(x) \frac{du(x; k)}{dx} \eta'(x) - b_k \frac{du(x; k)}{dx} \eta(x) - c_k(x) u(x; k) \eta(x) + f_k(x) \eta + u_{\bar{l}}(x; k) \eta(x) \right) dx + \left( (\gamma_{s^n} (s^n)')^k - \chi_{s^n}^k \right) \eta(s_k) + g_k^n \eta(0) = 0, \\ \forall \eta \in W_2^1[0, s_k] \quad (6)$$

3.  $u(x; k) \in W_2^1[0, s_k]$  iteratively continued to  $[0, l]$  as

$$u(x; k) = u(2^n s_k - x; k), \quad 2^{n-1} s_k \leq x \leq 2^n s_k, \quad n = \overline{1, n_k},$$

$$n_k \leq N = 1 + \log_2 \left[ \frac{l}{\delta} \right] \quad (7)$$

# Discrete Optimal Control Problem

$$\mathcal{I}_n([v]_n) = \beta_0 \tau \sum_{k=1}^n \left( u(0; k) - \nu_k \right)^2 + \beta_1 \tau \sum_{k=1}^n \left( u(s_k; k) - \mu_k \right)^2 \quad (8)$$

$$V_R^n = \{ [v]_n = ([s]_n, [g]_n) \in \mathbb{R}^{2n+2} : 0 < \delta \leq s_k \leq l, \\ \max(\|[s]_n\|_{w_2}^2; \|[g]_n\|_{w_1}^2) \leq R^2 \}$$

$[u([v]_n)]_n = (u(x; 0), u(x; 1), \dots, u(x; n))$  be a discrete state vector. Formulated discrete optimal control problem will be called Problem  $\mathcal{I}_n$ .

$$u^\tau(x, t) = u(x; k), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n},$$

$$\hat{u}^\tau(x, t) = u(x; k-1) + u_\tau(x; k)(t - t_{k-1}), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n}$$

$$\hat{u}^\tau(x, t) = u(x; n), \quad \text{if } t \geq T, \quad 0 \leq x \leq l.$$

$$u^\tau \in V_2(D), \quad \hat{u}^\tau \in W_2^{1,1}(D)$$

$$\begin{aligned} D &= \{(x, t) : 0 < x < l, 0 < t \leq T\} \\ a, b, c &\in L_\infty(D), f \in L_2(D), \\ \phi &\in W_2^1[0, s_0], \gamma, \chi \in W_2^{1,1}(D), \mu, \nu \in L_2[0, T], \\ \frac{\partial a}{\partial x} &\in L_\infty(D), \int_0^T \operatorname{ess\,sup}_{0 \leq x \leq l} \left| \frac{\partial a}{\partial t} \right| dt < +\infty. \end{aligned} \quad (9)$$

## Theorem 2

The Problem  $\mathcal{I}$  has a solution, i.e.

$$V_* = \{v \in V_R : \mathcal{J}(v) = \mathcal{J}_* \equiv \inf_{v \in V_R} \mathcal{J}(v)\} \neq \emptyset$$

# Convergence Theorem

## Theorem 3

*Sequence of discrete optimal control problems  $\mathcal{I}_n$  approximates the optimal control problem  $\mathcal{I}$  with respect to functional, i.e.*

$$\lim_{n \rightarrow +\infty} I_{n_*} = J_*, \quad (10)$$

where

$$I_{n_*} = \inf_{V_R^n} I_n([v]_n), \quad n = 1, 2, \dots$$

If  $[v]_{n_\epsilon} \in V_R^{n_\epsilon}$  is chosen such that

$$I_{n_*} \leq I_{n_\epsilon}([v]_{n_\epsilon}) \leq I_{n_*} + \epsilon_n, \quad \epsilon_n \downarrow 0,$$

then the sequence  $v_n = (s_n, g_n) = \mathcal{P}_n([v]_{n_\epsilon})$  converges to some element  $v_* = (s_*, g_*) \in V_*$  weakly in  $W_2^2[0, T] \times W_2^1[0, T]$ , and strongly in  $W_2^1[0, T] \times L_2[0, T]$ . In particular  $s_n$  converges to  $s_*$  uniformly on  $[0, T]$ . Moreover, piecewise linear interpolation  $\hat{u}^\tau$  of the discrete state vector  $[u[v]_{n_\epsilon}]_n$  converges to the solution  $u(x, t; v_*) \in W_2^{1,1}(\Omega_*)$  of the Neumann problem (2)-(5) weakly in  $W_2^{1,1}(\Omega_*)$ .



# First Energy Estimate and its Consequences

## Theorem 4

For all sufficiently small  $\tau$  discrete state vector  $[u([v]_n)]_n$  satisfies:

$$\max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=1}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx \leq$$

$$C \left( \|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (11)$$

$$\max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau^2 \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq$$

$$C \left( \|\phi\|_{W_2^1(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (12)$$

## Theorem 5

Let  $[v]_n \in V_R^n$ ,  $n = 1, 2, \dots$  be a sequence of discrete controls and the sequence  $\{\mathcal{P}_n([v]_n)\}$  converges strongly in  $W_2^1[0, T] \times L_2[0, T]$  to  $v = (s, g)$ . Then the sequence  $\{u^\tau\}$  converges as  $\tau \rightarrow 0$  weakly in  $W_2^{1,0}(\Omega)$  to weak solution  $u \in V_2^{1,0}(\Omega)$  of the problem (2)-(5), i.e. to the solution of the integral identity (??). Moreover,  $u$  satisfies the energy estimate

$$\|u\|_{V_2^{1,0}(D)}^2 \leq C \left( \|\phi\|_{L_2(0,s_0)}^2 + \|g\|_{L_2(0,T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,0}(D)}^2 + \|\chi\|_{W_2^{1,0}(D)}^2 \right) \quad (13)$$

## Corollary 6

For arbitrary  $v = (s, g) \in V_R$  there exists a weak solution  $u \in V_2^{1,0}(\Omega)$  of the problem (2)-(5) which satisfy the energy estimate (6):

$$\|u\|_{V_2^{1,0}(D)}^2 \leq C \left( \|\phi\|_{L_2(0,s_0)}^2 + \|g\|_{L_2(0,T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,0}(D)}^2 + \|\chi\|_{W_2^{1,0}(D)}^2 \right)$$

# Second Energy Estimate and its Consequences

## Theorem 7

For all sufficiently small  $\tau$  discrete state vector  $[u([v]_n)]_n$  satisfies the following stability estimation:

$$\begin{aligned} \max_{1 \leq k \leq n} \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq C \left[ \|\phi\|_{W_2^1[0, l]}^2 + \right. \\ \left. \|g^n\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \|\chi(s^n(t), t)\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \right. \\ \left. + \|f\|_{L_2(D)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right] \quad (14) \end{aligned}$$

$W_2^{\frac{1}{4}}[0, T]$  – Banach space of all elements of  $L_2[0, T]$  with finite norm

$$\|u\|_{W_2^{\frac{1}{4}}[0, T]} = \left( \|u\|_{L_2[0, T]}^2 + \int_0^T dt \int_0^T \frac{|u(t) - u(\tau)|^2}{|t - \tau|^{\frac{3}{2}}} d\tau \right)^{\frac{1}{2}}$$

## Theorem 8

Let  $[v]_n \in V_R^n, n = 1, 2, \dots$  be a sequence of discrete controls and the sequence  $\{\mathcal{P}_n([v]_n)\}$  converges weakly in  $W_2^2[0, T] \times W_2^1[0, T]$  to  $v = (s, g)$ . Then the sequence  $\{\hat{u}^\tau\}$  converges as  $\tau \rightarrow 0$  weakly in  $W_2^{1,1}(\Omega)$  to weak solution  $u \in W_2^{1,1}(\Omega)$  of the problem (2)-(5).

Moreover,  $u$  satisfies the energy estimate

$$\|u\|_{W_2^{1,1}(D)}^2 \leq C \left( \|\phi\|_{W_2^1(0, s_0)}^2 + \|g\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right) \quad (15)$$

## Corollary 9

For arbitrary  $v = (s, g) \in V_R$  there exists a weak solution  $u \in W_2^{1,1}(\Omega)$  of the problem (2)-(5) which satisfy the energy estimate

$$\|u\|_{W_2^{1,1}(D)}^2 \leq C \left( \|\phi\|_{W_2^1(0, s_0)}^2 + \|g\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right)$$

## Sketch of the Proof of Theorem 8

Second energy estimate implies

$$\|\hat{u}^\tau\|_{W_2^{1,1}(D)}^2 \leq C \left( \|\phi\|_{W_2^1(0,s_0)}^2 + \|g^n\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right)$$

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$$\|\hat{u}^\tau - u^\tau\|_{L_2(D)} = \frac{1}{3} \tau^3 \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \rightarrow 0, \quad \text{as } \tau \rightarrow 0$$



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# Proof of Existence Theorem

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Sequence  $v_n = (s_n, g_n)$  is weakly precompact in  $W_2^2[0, T] \times W_2^1[0, T]$ . Assume that the whole sequence  $v_n = (s_n, g_n)$  converge to some limit function  $v = (s, g) \in V_R$  weakly in  $W_2^2[0, T] \times W_2^1[0, T]$ , and hence, strongly in  $W_2^1[0, T] \times L_2[0, T]$ . Let  $u_n = u(x, t; v_n)$ ,  $u = u(x, t; v) \in W_2^{1,1}(D)$  are weak solutions of (2)-(5) in  $W_2^{1,1}(\Omega_n)$  and  $W_2^{1,1}(\Omega)$  respectively. By Corollary 9, both satisfy energy estimation (15) with  $g_n$  and  $g$  on the right-hand side respectively.

# Proof of Existence Theorem

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Since  $v_n \in V_R$ ,  $\|u_n\|_{W_2^{1,1}(D)}$  is uniformly bounded. Hence, the sequence

$\Delta u = u_n - u$  satisfies

$$\|\Delta u\|_{W_2^{1,1}(D)} \leq C \tag{16}$$

uniformly with respect to  $n$ .

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uniformly with respect to  $n$ . Accordingly,  $\{\Delta u\}$  is weakly precompact in  $W_2^{1,1}(D)$ . Without loss of generality assume that the whole sequence  $u_n - u$  converges weakly in  $W_2^{1,1}(D)$  to some function  $v \in W_2^{1,1}(D)$ . Let us subtract integral identities for  $u_n$  and  $u$ , by assuming that the fixed test function  $\Phi$  belongs to  $W_2^{1,1}(D)$ .

# Proof of Existence Theorem

$$\begin{aligned} & \int_0^T \int_0^{s(t)} \left\{ a \Delta u_x \Phi_x - b \Delta u_x \Phi - c \Delta u \Phi + \Delta u_t \Phi_x \right\} dx dt + \int_0^T (g_n - g) \Phi(0, t) \\ & + \int_0^T [\gamma(s_n(t), t) s'_n(t) - \gamma(s(t), t) s'(t) - \chi(s_n(t), t) + \chi(s(t), t)] \Phi(s(t), t) dt \\ & + \int_0^T \int_{s(t)}^{s_n(t)} \{ a (u_n)_x \Phi_x - b (u_n)_x \Phi - c u_n \Phi + (u_n)_t \Phi + f \Phi \} dx dt \\ & + \int_0^T [\gamma(s_n(t), t) s'_n(t) - \chi(s_n(t), t)] [\Phi(s_n(t), t) - \Phi(s(t), t)] dt = 0 \end{aligned} \tag{17}$$



# Proof of Existence Theorem

By using energy estimate (15), and continuity of traces  $\gamma(s(t), t), \chi(s(t), t)$  of elements  $\gamma, \chi \in W_2^{1,1}(D)$ , strongly in  $L_2[0, T]$  with respect to  $s \in W_2^1[0, T]$ , passing to the limit as  $n \rightarrow +\infty$ , from (17) it follows that the weak limit function  $v$  satisfies the integral identity

$$\int_0^T \int_0^{s(t)} \{av_x \Phi_x - bv_x \Phi + cv \Phi + v_t \Phi\} dx dt = 0 \quad (18)$$

for arbitrary  $\Phi \in W_2^{1,1}(D)$ .

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# Proof of Existence Theorem

From Sobolev trace theorem it follows that

$$\|u_n(0, t) - u(0, t)\|_{L^2[0, T]} \rightarrow 0, \quad \|u_n(s(t), t) - u(s(t), t)\|_{L^2[0, T]} \rightarrow 0 \quad \text{as } n \rightarrow \infty,$$

$$\begin{aligned} \|u_n(s_n(t), t) - u(s(t), t)\|_{L^2[0, T]} &\leq \|u_n(s_n(t), t) - u_n(s(t), t)\|_{L^2[0, T]} \\ &\quad + \|u_n(s(t), t) - u(s(t), t)\|_{L^2[0, T]} \rightarrow 0 \quad \text{as } n \rightarrow \infty. \end{aligned}$$

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Hence, we have

$$\mathcal{J}(v) = \lim_{n \rightarrow \infty} \mathcal{J}(v_n) = \mathcal{J}_*$$

and  $v$  is a solution of the Problem I. Theorem is proved.

# Proof of Convergence Theorem

## Proof of Lemma 10

### Lemma 10

Let  $\mathcal{J}_*(\pm\epsilon) = \inf_{V_{R\pm\epsilon}} \mathcal{J}(v)$ ,  $\epsilon > 0$ . Then

$$\lim_{\epsilon \rightarrow 0} \mathcal{J}_*(\epsilon) = \mathcal{J}_* = \lim_{\epsilon \rightarrow 0} \mathcal{J}_*(-\epsilon) \quad (19)$$



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Choose  $v_\epsilon \in V_{R+\epsilon}$  such that

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$$s_{\epsilon'} \rightarrow s_* \text{ weakly in } W_2^2[0, T], \quad g_{\epsilon'} \rightarrow g_* \text{ weakly in } W_2^1[0, T], \quad \epsilon' \rightarrow 0$$

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ .

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ . By the weak continuity of  $J$ ,

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J(v_*)$$

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ . By the weak continuity of  $J$ ,

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J(v_*)$$

Since also

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it follows that

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The first inequality in (19) follows. To prove the second inequality, fix  $\epsilon_0 > 0$ ,  $\tilde{v} = (\tilde{s}, \tilde{g} \in V_{R-\epsilon_0})$ .

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$$v_k = (s_k, g_k) := \alpha_k \tilde{v} + (1 - \alpha_k)v_*$$

where  $J(v_*) = J_*$ .

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ . By the weak continuity of  $J$ ,

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where  $J(v_*) = J_*$ . It follows that  $J(v_k) \rightarrow J_*$ . For fixed  $k$ , choose  $\epsilon$  such that  $0 < \epsilon < \epsilon_0 \alpha_k$ .

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Proof of Lemma 10, cont'd

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$$J_*(-\epsilon) \leq J(v_k), \quad 0 < \epsilon < \epsilon_0 \alpha_k$$

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ . By the weak continuity of  $J$ ,

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$$\lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J(v_k)$$

# Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit  $v_* = (s_*, g_*) \in V_R$ . By the weak continuity of  $J$ ,

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J(v_*)$$

Since also

$$\lim_{\epsilon \rightarrow 0} (J(v_\epsilon) - J_*(\epsilon)) = 0,$$

it follows that

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J_*$$

The first inequality in (19) follows. To prove the second inequality, fix  $\epsilon_0 > 0$ ,  $\tilde{v} = (\tilde{s}, \tilde{g} \in V_{R-\epsilon_0})$ . Let  $\alpha_k$  satisfy  $0 < \alpha_k < 1$ ,  $\lim_{k \rightarrow +\infty} \alpha_k = 0$  and set

$$v_k = (s_k, g_k) := \alpha_k \tilde{v} + (1 - \alpha_k)v_*$$

where  $J(v_*) = J_*$ . It follows that  $J(v_k) \rightarrow J_*$ . For fixed  $k$ , choose  $\epsilon$  such that  $0 < \epsilon < \epsilon_0 \alpha_k$ . Then

$$J_*(-\epsilon) \leq J(v_k), \quad 0 < \epsilon < \epsilon_0 \alpha_k$$

$$\lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J(v_k) \quad \text{pass } k \rightarrow \infty \text{ to find } \lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J_*$$

# Proof of Convergence Theorem

## Proof of Lemma 11

### Lemma 11

For arbitrary  $v = (s, g) \in V_R$ ,

$$\lim_{n \rightarrow \infty} \mathcal{I}_n(\mathcal{Q}_n(v)) = \mathcal{J}(v) \quad (20)$$

# Proof of Convergence Theorem

## Proof of Lemma 11

### Lemma 11

For arbitrary  $v = (s, g) \in V_R$ ,

$$\lim_{n \rightarrow \infty} \mathcal{I}_n(Q_n(v)) = \mathcal{J}(v) \quad (20)$$

**Proof:** Let  $v \in V_R$ ,  $u = u(x, t; v)$ ,  $Q_n(v) = [v]_n$ , and  $[u([v]_n)]_n$  be the corresponding discrete state vector.



# Proof of Convergence Theorem

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$$\hat{u}^\tau(0, t) \rightarrow u(0, t), \quad \hat{u}^\tau(s(t), t) \rightarrow u(s(t), t) \text{ in } L_2[0, T]$$

# Proof of Convergence Theorem

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We now show  $\{u^\tau(0, t)\}$ ,  $\{u^\tau(s(t), t)\}$  converge strongly in  $L_2[0, T]$ .

# Proof of Convergence Theorem

## Proof of Lemma 11

### Lemma 11

For arbitrary  $v = (s, g) \in V_R$ ,

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We now show  $\{u^\tau(0, t)\}$ ,  $\{u^\tau(s(t), t)\}$  converge strongly in  $L_2[0, T]$ . It is enough to show that  $\{u^\tau\}$  and  $\{\hat{u}^\tau\}$  are equivalent in the strong topology of  $W_2^{1,0}(\Omega)$ . In theorem 8, it is proved that they are equivalent in the strong topology of  $L_2(D)$ .

# Proof of Convergence Theorem

## Proof of Lemma 11

### Lemma 11

For arbitrary  $v = (s, g) \in V_R$ ,

$$\lim_{n \rightarrow \infty} \mathcal{I}_n(\mathcal{Q}_n(v)) = \mathcal{J}(v) \quad (20)$$

**Proof:** Let  $v \in V_R$ ,  $u = u(x, t; v)$ ,  $\mathcal{Q}_n(v) = [v]_n$ , and  $[u([v]_n)]_n$  be the corresponding discrete state vector. In theorem 8, it is proved that  $\{\hat{u}^\tau\} \rightarrow u$  weakly in  $W_2^{1,1}(\Omega)$ .

$$\hat{u}^\tau(0, t) \rightarrow u(0, t), \quad \hat{u}^\tau(s(t), t) \rightarrow u(s(t), t) \text{ in } L_2[0, T]$$

We now show  $\{u^\tau(0, t)\}$ ,  $\{u^\tau(s(t), t)\}$  converge strongly in  $L_2[0, T]$ . It is enough to show that  $\{u^\tau\}$  and  $\{\hat{u}^\tau\}$  are equivalent in the strong topology of  $W_2^{1,0}(\Omega)$ . In theorem 8, it is proved that they are equivalent in the strong topology of  $L_2(D)$ . It remains to show that  $\{u_x^\tau\}$  and  $\{\hat{u}_x^\tau\}$  are equivalent in the strong topology of  $L_2(\Omega)$ .

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left( \frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left( \frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

where  $s_k = s^n(t_k)$ ,  $s_n$  is the first component of  $P_n([v]_n)$  and

$$\Gamma_n = \bigcup_{k=1}^n \{t_{k-1} < t \leq t_k; \min(s_{k-1}; s_k) < x < s(t)\}$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left( \frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

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$$\Gamma_n = \bigcup_{k=1}^n \{t_{k-1} < t \leq t_k; \min(s_{k-1}; s_k) < x < s(t)\}$$

Since  $s^n$  converges uniformly on  $[0, T]$ ,  $|\Gamma_n| \rightarrow 0$ .



# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left( \frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

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Since  $s^n$  converges uniformly on  $[0, T]$ ,  $|\Gamma_n| \rightarrow 0$ . By theorems 5 and 8, the integrand is uniformly bounded, and hence the second term on the RHS  $\rightarrow 0$ .

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left( \frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

where  $s_k = s^n(t_k)$ ,  $s_n$  is the first component of  $P_n([v]_n)$  and

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Since  $s^n$  converges uniformly on  $[0, T]$ ,  $|\Gamma_n| \rightarrow 0$ . By theorems 5 and 8, the integrand is uniformly bounded, and hence the second term on the RHS  $\rightarrow 0$ . The stability estimation implies the first term on the RHS  $\rightarrow 0$ , and hence  $\{u_x^\tau\}$   $\{\hat{u}_x^\tau\}$  are equivalent in  $L_2(\Omega)$ .

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let  $\nu^\tau(t) = \nu^k$ ,  $\mu^\tau(t) = \mu^k$  if  $t_{k-1} < t \leq t_k$ ,  $k = 1, \dots, n$ .

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let  $\nu^\tau(t) = \nu^k$ ,  $\mu^\tau(t) = \mu^k$  if  $t_{k-1} < t \leq t_k$ ,  $k = 1, \dots, n$ .

$$\|\nu^k - \nu\|_{L_2[0,T]} \rightarrow 0, \quad \|\mu^k - \mu\|_{L_2[0,T]} \rightarrow 0 \text{ as } \tau \rightarrow 0$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let  $\nu^\tau(t) = \nu^k$ ,  $\mu^\tau(t) = \mu^k$  if  $t_{k-1} < t \leq t_k$ ,  $k = 1, \dots, n$ .

$$\|\nu^k - \nu\|_{L_2[0,T]} \rightarrow 0, \quad \|\mu^k - \mu\|_{L_2[0,T]} \rightarrow 0 \text{ as } \tau \rightarrow 0$$

Estimate the first term in  $\mathcal{I}_n(Q_n(v))$  as

$$\beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 = \beta_0 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(0; k) - \nu^k|^2 dt$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let  $\nu^\tau(t) = \nu^k$ ,  $\mu^\tau(t) = \mu^k$  if  $t_{k-1} < t \leq t_k$ ,  $k = 1, \dots, n$ .

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Estimate the first term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 &= \beta_0 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(0; k) - \nu^k|^2 dt \\ &= \beta_0 \int_0^T |u^\tau(0, t) - \nu^\tau|^2 dt \end{aligned}$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let  $\nu^\tau(t) = \nu^k$ ,  $\mu^\tau(t) = \mu^k$  if  $t_{k-1} < t \leq t_k$ ,  $k = 1, \dots, n$ .

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Estimate the first term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 &= \beta_0 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(0; k) - \nu^k|^2 dt \\ &= \beta_0 \int_0^T |u^\tau(0, t) - \nu^\tau|^2 dt \end{aligned}$$

$$\lim_{n \rightarrow \infty} \beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 = \beta_0 \|u(0, t) - \nu(t)\|_{L_2[0,T]}^2$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Estimate the second term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 &= 2\beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} (u^\tau(s(t), t) - \mu^\tau(t)) dx dt + \\ &+ \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(s(t); k) - \mu^k|^2 dt + \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \left( \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} dx \right)^2 dt \end{aligned}$$



# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Estimate the second term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 &= 2\beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} (u^\tau(s(t), t) - \mu^\tau(t)) dx dt + \\ &+ \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(s(t); k) - \mu^k|^2 dt + \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \left( \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} dx \right)^2 dt \end{aligned}$$

Set the three integrals on the RHS as  $I_1$ ,  $I_2$ , and  $I_3$ .

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Estimate the second term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 &= 2\beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} (u^\tau(s(t), t) - \mu^\tau(t)) dx dt + \\ &+ \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(s(t); k) - \mu^k|^2 dt + \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \left( \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} dx \right)^2 dt \end{aligned}$$

Set the three integrals on the RHS as  $I_1$ ,  $I_2$ , and  $I_3$ .

$$\lim_{n \rightarrow \infty} I_2 = \beta_1 \int_0^T |u^\tau(s(t), t) - \mu^\tau(t)|^2 dt = \beta_1 \int_0^T |u(s(t), t) - \mu(t)|^2 dt$$

# Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Estimate the second term in  $\mathcal{I}_n(Q_n(v))$  as

$$\begin{aligned} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 &= 2\beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} (u^\tau(s(t), t) - \mu^\tau(t)) dx dt + \\ &+ \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(s(t); k) - \mu^k|^2 dt + \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \left( \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} dx \right)^2 dt \end{aligned}$$

Set the three integrals on the RHS as  $I_1$ ,  $I_2$ , and  $I_3$ .

$$\lim_{n \rightarrow \infty} I_2 = \beta_1 \int_0^T |u^\tau(s(t), t) - \mu^\tau(t)|^2 dt = \beta_1 \int_0^T |u(s(t), t) - \mu(t)|^2 dt$$

Since  $\|(u^\tau)_x\|_{L_2(D)}$  and  $\|u^\tau(s(t), t) - \mu^\tau\|_{L_2[0, T]}$  are unif. bounded and  $\{s^n\}$  converges uniformly to  $s$  on  $[0, T]$ ,

$$\lim_{n \rightarrow \infty} I_1 = 0, \quad \lim_{n \rightarrow \infty} I_3 = 0$$

# Proof of Convergence Theorem

## Lemma 12

Hence

$$\lim_{\tau \rightarrow 0} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 = \beta_1 \int_0^T |u(s(t), t) - \mu(t)|^2 dt$$

Lemma is proved.

## Lemma 12

For arbitrary  $[v]_n \in V_R^n$

$$\lim_{n \rightarrow \infty} \left( \mathcal{J}(\mathcal{P}_n([v]_n)) - \mathcal{I}_n([v]_n) \right) = 0 \quad (21)$$