

Optimal Control and Inverse Problems for PDEs. Inverse Stefan Problem - Part 3

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Inverse Stefan Problem (ISP): Find the functions $u(x, t)$ and $s(t)$ and the boundary heat flux $g(t)$ satisfying conditions

$$(a(x, t)u_x)_x + b(x, t)u_x + c(x, t)u - u_t = f(x, t), \quad \text{for } (x, t) \in \Omega$$

$$u(x, 0) = \phi(x), \quad 0 \leq x \leq s(0) = s_0$$

$$a(0, t)u_x(0, t) = g(t), \quad 0 \leq t \leq T$$

$$a(s(t), t)u_x(s(t), t) + \gamma(s(t), t)s'(t) = \chi(s(t), t), \quad 0 \leq t \leq T$$

$$u(s(t), t) = \mu(t), \quad 0 \leq t \leq T$$

$$u(0, t) = \nu(t), \quad \text{for } 0 \leq t \leq T$$

Optimal Control Problem

$$\mathcal{J}(v) = \beta_0 \|u(0, t) - \nu(t)\|_{L_2[0, T]}^2 + \beta_1 \|u(s(t), t) - \mu(t)\|_{L_2[0, T]}^2 \quad (1)$$

$$V_R = \left\{ v = (s, g) \in W_2^2[0, T] \times W_2^1[0, T] : \delta \leq s(t) \leq l, \right. \\ \left. s(0) = s_0, \max(\|s\|_{W_2^2}; \|g\|_{W_2^1}) \leq R \right\}$$

$$(a(x, t)u_x)_x + b(x, t)u_x + c(x, t)u - u_t = f(x, t), \quad \text{for } (x, t) \in \Omega \quad (2)$$

$$u(x, 0) = \phi(x), \quad 0 \leq x \leq s(0) = s_0 \quad (3)$$

$$a(0, t)u_x(0, t) = g(t), \quad 0 \leq t \leq T \quad (4)$$

$$a(s(t), t)u_x(s(t), t) + \gamma(s(t), t)s'(t) = \chi(s(t), t), \quad 0 \leq t \leq T \quad (5)$$

$$\Omega = \{(x, t) : 0 < x < s(t), 0 < t \leq T\}$$

Discrete Optimal Control Problem

$$\omega_\tau = \{t_j = j \cdot \tau, j = 0, 1, \dots, n\}$$

$$V_R^n = \{[v]_n = ([s]_n, [g]_n) \in \mathbb{R}^{2n+2} : 0 < \delta \leq s_k \leq l,$$

$$\max(\|[s]_n\|_{w_2}^2; \|[g]_n\|_{w_1}^2) \leq R^2\}$$

$$[s]_n = (s_0, s_1, \dots, s_n) \in \mathbb{R}^{n+1}, [g]_n = (g_0, g_1, \dots, g_n) \in \mathbb{R}^{n+1}$$

$$\|[s]_n\|_{w_2}^2 = \sum_{k=0}^{n-1} \tau s_k^2 + \sum_{k=1}^n \tau s_{\bar{t},k}^2 + \sum_{k=1}^{n-1} \tau s_{\bar{t}\bar{t},k}^2, \|[g]_n\|_{w_1}^2 = \sum_{k=0}^{n-1} \tau g_k^2 + \sum_{k=1}^n \tau g_{\bar{t},k}^2.$$

$$s_{\bar{t},k} = \frac{s_k - s_{k-1}}{\tau}, s_{t,k} = \frac{s_{k+1} - s_k}{\tau}, s_{\bar{t}\bar{t},k} = \frac{s_{k+1} - 2s_k + s_{k-1}}{\tau^2}.$$

Definition 1

$[u([v]_n)]_n = (u(x; 0), u(x; 1), \dots, u(x; n))$ is called discrete state vector if

1. $u(x; 0) = \phi(x) \in W_2^1[0, s_0]$;
2. $u(x; k) \in W_2^1[0, s_k]$ satisfy the integral identity

$$\int_0^{s_k} \left(a_k(x) \frac{du(x; k)}{dx} \eta'(x) - b_k \frac{du(x; k)}{dx} \eta(x) - c_k(x) u(x; k) \eta(x) + f_k(x) \eta + u_{\bar{l}}(x; k) \eta(x) \right) dx + \left((\gamma_{s^n} (s^n)')^k - \chi_{s^n}^k \right) \eta(s_k) + g_k^n \eta(0) = 0, \\ \forall \eta \in W_2^1[0, s_k] \quad (6)$$

3. $u(x; k) \in W_2^1[0, s_k]$ iteratively continued to $[0, l]$ as

$$u(x; k) = u(2^n s_k - x; k), \quad 2^{n-1} s_k \leq x \leq 2^n s_k, \quad n = \overline{1, n_k},$$

$$n_k \leq N = 1 + \log_2 \left[\frac{l}{\delta} \right] \quad (7)$$

Discrete Optimal Control Problem

$$\mathcal{I}_n([v]_n) = \beta_0 \tau \sum_{k=1}^n \left(u(0; k) - \nu_k \right)^2 + \beta_1 \tau \sum_{k=1}^n \left(u(s_k; k) - \mu_k \right)^2 \quad (8)$$

$$V_R^n = \{ [v]_n = ([s]_n, [g]_n) \in \mathbb{R}^{2n+2} : 0 < \delta \leq s_k \leq l, \\ \max(\| [s]_n \|_{w_2^2}, \| [g]_n \|_{w_1^2}) \leq R^2 \}$$

$[u([v]_n)]_n = (u(x; 0), u(x; 1), \dots, u(x; n))$ be a discrete state vector. Formulated discrete optimal control problem will be called Problem \mathcal{I}_n .

$$u^\tau(x, t) = u(x; k), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n},$$

$$\hat{u}^\tau(x, t) = u(x; k-1) + u_\tau(x; k)(t - t_{k-1}), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n}$$

$$\hat{u}^\tau(x, t) = u(x; n), \quad \text{if } t \geq T, \quad 0 \leq x \leq l.$$

$$u^\tau \in V_2(D), \quad \hat{u}^\tau \in W_2^{1,1}(D)$$

$$\begin{aligned} D &= \{(x, t) : 0 < x < l, 0 < t \leq T\} \\ a, b, c &\in L_\infty(D), f \in L_2(D), \\ \phi &\in W_2^1[0, s_0], \gamma, \chi \in W_2^{1,1}(D), \mu, \nu \in L_2[0, T], \\ \frac{\partial a}{\partial x} &\in L_\infty(D), \int_0^T \operatorname{ess\,sup}_{0 \leq x \leq l} \left| \frac{\partial a}{\partial t} \right| dt < +\infty. \end{aligned} \quad (9)$$

Theorem 2

The Problem \mathcal{I} has a solution, i.e.

$$V_* = \{v \in V_R : \mathcal{J}(v) = \mathcal{J}_* \equiv \inf_{v \in V_R} \mathcal{J}(v)\} \neq \emptyset$$

Convergence Theorem

Theorem 3

Sequence of discrete optimal control problems \mathcal{I}_n approximates the optimal control problem \mathcal{I} with respect to functional, i.e.

$$\lim_{n \rightarrow +\infty} I_{n_*} = J_*, \quad (10)$$

where

$$I_{n_*} = \inf_{V_R^n} I_n([v]_n), \quad n = 1, 2, \dots$$

If $[v]_{n_\epsilon} \in V_R^{n_\epsilon}$ is chosen such that

$$I_{n_*} \leq I_n([v]_{n_\epsilon}) \leq I_{n_*} + \epsilon_n, \quad \epsilon_n \downarrow 0,$$

then the sequence $v_n = (s_n, g_n) = \mathcal{P}_n([v]_{n_\epsilon})$ converges to some element $v_ = (s_*, g_*) \in V_*$ weakly in $W_2^2[0, T] \times W_2^1[0, T]$, and strongly in $W_2^1[0, T] \times L_2[0, T]$. In particular s_n converges to s_* uniformly on $[0, T]$. Moreover, piecewise linear interpolation \hat{u}^τ of the discrete state vector $[u[v]_{n_\epsilon}]_n$ converges to the solution $u(x, t; v_*) \in W_2^{1,1}(\Omega_*)$ of the Neumann problem (2)-(5) weakly in $W_2^{1,1}(\Omega_*)$.*

First Energy Estimate and its Consequences

Theorem 4

For all sufficiently small τ discrete state vector $[u([v]_n)]_n$ satisfies:

$$\max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=1}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx \leq$$

$$C \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (11)$$

$$\max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau^2 \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq$$

$$C \left(\|\phi\|_{W_2^1(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (12)$$

Theorem 5

Let $[v]_n \in V_R^n$, $n = 1, 2, \dots$ be a sequence of discrete controls and the sequence $\{\mathcal{P}_n([v]_n)\}$ converges strongly in $W_2^1[0, T] \times L_2[0, T]$ to $v = (s, g)$. Then the sequence $\{u^\tau\}$ converges as $\tau \rightarrow 0$ weakly in $W_2^{1,0}(\Omega)$ to weak solution $u \in V_2^{1,0}(\Omega)$ of the problem (2)-(5), i.e. to the solution of the integral identity (??). Moreover, u satisfies the energy estimate

$$\|u\|_{V_2^{1,0}(D)}^2 \leq C \left(\|\phi\|_{L_2(0,s_0)}^2 + \|g\|_{L_2(0,T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,0}(D)}^2 + \|\chi\|_{W_2^{1,0}(D)}^2 \right) \quad (13)$$

Corollary 6

For arbitrary $v = (s, g) \in V_R$ there exists a weak solution $u \in V_2^{1,0}(\Omega)$ of the problem (2)-(5) which satisfy the energy estimate (6):

$$\|u\|_{V_2^{1,0}(D)}^2 \leq C \left(\|\phi\|_{L_2(0,s_0)}^2 + \|g\|_{L_2(0,T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,0}(D)}^2 + \|\chi\|_{W_2^{1,0}(D)}^2 \right)$$

Second Energy Estimate and its Consequences

Theorem 7

For all sufficiently small τ discrete state vector $[u([v]_n)]_n$ satisfies the following stability estimation:

$$\begin{aligned} \max_{1 \leq k \leq n} \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq C \left[\|\phi\|_{W_2^1[0, l]}^2 + \right. \\ \left. \|g^n\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \|\chi(s^n(t), t)\|_{W_2^{\frac{1}{4}}[0, T]}^2 + \right. \\ \left. + \|f\|_{L_2(D)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right] \quad (14) \end{aligned}$$

$W_2^{\frac{1}{4}}[0, T]$ – Banach space of all elements of $L_2[0, T]$ with finite norm

$$\|u\|_{W_2^{\frac{1}{4}}[0, T]} = \left(\|u\|_{L_2[0, T]}^2 + \int_0^T dt \int_0^T \frac{|u(t) - u(\tau)|^2}{|t - \tau|^{\frac{3}{2}}} d\tau \right)^{\frac{1}{2}}$$

Theorem 8

Let $[v]_n \in V_R^n, n = 1, 2, \dots$ be a sequence of discrete controls and the sequence $\{\mathcal{P}_n([v]_n)\}$ converges weakly in $W_2^2[0, T] \times W_2^1[0, T]$ to $v = (s, g)$. Then the sequence $\{\hat{u}^\tau\}$ converges as $\tau \rightarrow 0$ weakly in $W_2^{1,1}(\Omega)$ to weak solution $u \in W_2^{1,1}(\Omega)$ of the problem (2)-(5).

Moreover, u satisfies the energy estimate

$$\|u\|_{W_2^{1,1}(D)}^2 \leq C \left(\|\phi\|_{W_2^1(0, s_0)}^2 + \|g\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right) \quad (15)$$

Corollary 9

For arbitrary $v = (s, g) \in V_R$ there exists a weak solution $u \in W_2^{1,1}(\Omega)$ of the problem (2)-(5) which satisfy the energy estimate

$$\|u\|_{W_2^{1,1}(D)}^2 \leq C \left(\|\phi\|_{W_2^1(0, s_0)}^2 + \|g\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right)$$

Sketch of the Proof of Theorem 8

Second energy estimate implies

$$\|\hat{u}^\tau\|_{W_2^{1,1}(D)}^2 \leq C \left(\|\phi\|_{W_2^1(0,s_0)}^2 + \|g^n\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right)$$

$\Rightarrow \{\hat{u}^\tau\}$ is weakly compact in $W_2^{1,1}(D) \Rightarrow$ strongly compact in $L_2(D)$

Let u be a weak limit point of $\{\hat{u}^\tau\}$ in $W_2^{1,1}(D) \Rightarrow u$ is a strong limit point of $\{\hat{u}^\tau\}$ in $L_2(D)$

$$\|\hat{u}^\tau - u^\tau\|_{L_2(D)} = \frac{1}{3}\tau^3 \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \rightarrow 0, \quad \text{as } \tau \rightarrow 0$$

$\Rightarrow u$ is a strong limit of $\{u^\tau\}$ in $L_2(D) \Rightarrow u$ is a unique weak solution of the problem (2)-(5) from $V_2^{1,0}(\Omega) \Rightarrow \{\hat{u}^\tau\}$ converges weakly in $W_2^{1,1}(\Omega)$ to $u \Rightarrow u$ is the weak solution of (2)-(5) from $W_2^{1,1}(\Omega) \Rightarrow$

$$\|u\|_{W_2^{1,1}(D)}^2 \leq C \left(\|\phi\|_{W_2^1(0,s_0)}^2 + \|g\|_{W_2^{\frac{1}{4}}}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,1}(D)}^2 + \|\chi\|_{W_2^{1,1}(D)}^2 \right)$$

Proof of Existence Theorem

Let $\{v_n\} \in V_R$ be a minimizing sequence

$$\lim_{n \rightarrow \infty} \mathcal{J}(v_n) = \mathcal{J}_*$$

Sequence $v_n = (s_n, g_n)$ is weakly precompact in $W_2^2[0, T] \times W_2^1[0, T]$. Assume that the whole sequence $v_n = (s_n, g_n)$ converge to some limit function $v = (s, g) \in V_R$ weakly in $W_2^2[0, T] \times W_2^1[0, T]$, and hence, strongly in $W_2^1[0, T] \times L_2[0, T]$. Let $u_n = u(x, t; v_n)$, $u = u(x, t; v) \in W_2^{1,1}(D)$ are weak solutions of (2)-(5) in $W_2^{1,1}(\Omega_n)$ and $W_2^{1,1}(\Omega)$ respectively. By Corollary 9, both satisfy energy estimation (15) with g_n and g on the right-hand side respectively. Since $v_n \in V_R$, $\|u_n\|_{W_2^{1,1}(D)}$ is uniformly bounded. Hence, the sequence $\Delta u = u_n - u$ satisfies

$$\|\Delta u\|_{W_2^{1,1}(D)} \leq C \quad (16)$$

uniformly with respect to n . Accordingly, $\{\Delta u\}$ is weakly precompact in $W_2^{1,1}(D)$. Without loss of generality assume that the whole sequence $u_n - u$ converges weakly in $W_2^{1,1}(D)$ to some function $v \in W_2^{1,1}(D)$. Let us subtract integral identities for u_n and u , by assuming that the fixed test function Φ belongs to $W_2^{1,1}(D)$.

Proof of Existence Theorem

$$\begin{aligned} & \int_0^T \int_0^{s(t)} \left\{ a \Delta u_x \Phi_x - b \Delta u_x \Phi - c \Delta u \Phi + \Delta u_t \Phi_x \right\} dx dt + \int_0^T (g_n - g) \Phi(0, t) \\ & + \int_0^T [\gamma(s_n(t), t) s'_n(t) - \gamma(s(t), t) s'(t) - \chi(s_n(t), t) + \chi(s(t), t)] \Phi(s(t), t) dt \\ & + \int_0^T \int_{s(t)}^{s_n(t)} \{ a(u_n)_x \Phi_x - b(u_n)_x \Phi - c u_n \Phi + (u_n)_t \Phi + f \Phi \} dx dt \\ & + \int_0^T [\gamma(s_n(t), t) s'_n(t) - \chi(s_n(t), t)] [\Phi(s_n(t), t) - \Phi(s(t), t)] dt = 0 \end{aligned} \tag{17}$$

Proof of Existence Theorem

By using energy estimate (15), and continuity of traces $\gamma(s(t), t), \chi(s(t), t)$ of elements $\gamma, \chi \in W_2^{1,1}(D)$, strongly in $L_2[0, T]$ with respect to $s \in W_2^1[0, T]$, passing to the limit as $n \rightarrow +\infty$, from (17) it follows that the weak limit function v satisfies the integral identity

$$\int_0^T \int_0^{s(t)} \{av_x \Phi_x - bv_x \Phi + cv \Phi + v_t \Phi\} dx dt = 0 \quad (18)$$

for arbitrary $\Phi \in W_2^{1,1}(D)$. Since, any element $\Phi \in W_2^{1,1}(\Omega)$ can be continued to D as element of $W_2^{1,1}(D)$, (18) is valid for arbitrary $\Phi \in W_2^{1,1}(\Omega)$. Hence, v is a weak solution from $W_2^{1,1}(\Omega)$ of the problem (2)-(5) with $f = g = \gamma = \chi = 0$. From (15) and uniqueness it follows that $v = 0$. Thus u_n converges to u weakly in $W_2^{1,1}(D)$.

Proof of Existence Theorem

From Sobolev trace theorem it follows that

$$\|u_n(0, t) - u(0, t)\|_{L^2[0, T]} \rightarrow 0, \quad \|u_n(s(t), t) - u(s(t), t)\|_{L^2[0, T]} \rightarrow 0 \quad \text{as } n \rightarrow \infty,$$

$$\begin{aligned} \|u_n(s_n(t), t) - u(s(t), t)\|_{L^2[0, T]} &\leq \|u_n(s_n(t), t) - u_n(s(t), t)\|_{L^2[0, T]} \\ &\quad + \|u_n(s(t), t) - u(s(t), t)\|_{L^2[0, T]} \rightarrow 0 \quad \text{as } n \rightarrow \infty. \end{aligned}$$

Hence, we have

$$\mathcal{J}(v) = \lim_{n \rightarrow \infty} \mathcal{J}(v_n) = \mathcal{J}_*$$

and v is a solution of the Problem I. Theorem is proved.

Proof of Convergence Theorem

Proof of Lemma 10

Lemma 10

Let $\mathcal{J}_*(\pm\epsilon) = \inf_{V_{R\pm\epsilon}} \mathcal{J}(v)$, $\epsilon > 0$. Then

$$\lim_{\epsilon \rightarrow 0} \mathcal{J}_*(\epsilon) = \mathcal{J}_* = \lim_{\epsilon \rightarrow 0} \mathcal{J}_*(-\epsilon) \quad (19)$$

Proof: For $0 < \epsilon_1 < \epsilon_2$,

$$J_*(\epsilon_2) \leq J_*(\epsilon_1) \leq J_* \leq J_*(-\epsilon_1) \leq J_*(-\epsilon_2)$$

$$\lim_{\epsilon \rightarrow 0} J_*(\epsilon) \leq J_* \quad \lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \geq J_* \text{ exist.}$$

Choose $v_\epsilon \in V_{R+\epsilon}$ such that

$$\lim_{\epsilon \rightarrow 0} (J(v_\epsilon) - J_*(\epsilon)) = 0$$

$v_\epsilon = (s_\epsilon, g_\epsilon)$ is weakly precompact in $W_2^2[0, T] \times W_2^1[0, T]$ so, there exists ϵ' such that

$$s_{\epsilon'} \rightarrow s_* \text{ weakly in } W_2^2[0, T], \quad g_{\epsilon'} \rightarrow g_* \text{ weakly in } W_2^1[0, T], \quad \epsilon' \rightarrow 0$$

Proof of Convergence Theorem

Proof of Lemma 10, cont'd

The limit $v_* = (s_*, g_*) \in V_R$. By the weak continuity of J ,

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J(v_*)$$

Since also

$$\lim_{\epsilon \rightarrow 0} (J(v_\epsilon) - J_*(\epsilon)) = 0,$$

it follows that

$$\lim_{\epsilon' \rightarrow 0} J(v_{\epsilon'}) = J_*$$

The first inequality in (19) follows. To prove the second inequality, fix $\epsilon_0 > 0$, $\tilde{v} = (\tilde{s}, \tilde{g} \in V_{R-\epsilon_0})$. Let α_k satisfy $0 < \alpha_k < 1$, $\lim_{k \rightarrow +\infty} \alpha_k = 0$ and set

$$v_k = (s_k, g_k) := \alpha_k \tilde{v} + (1 - \alpha_k)v_*$$

where $J(v_*) = J_*$. It follows that $J(v_k) \rightarrow J_*$. For fixed k , choose ϵ such that $0 < \epsilon < \epsilon_0 \alpha_k$. Then

$$J_*(-\epsilon) \leq J(v_k), \quad 0 < \epsilon < \epsilon_0 \alpha_k$$

$$\lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J(v_k) \quad \text{pass } k \rightarrow \infty \text{ to find } \lim_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J_*$$

Proof of Convergence Theorem

Proof of Lemma 11

Lemma 11

For arbitrary $v = (s, g) \in V_R$,

$$\lim_{n \rightarrow \infty} \mathcal{I}_n(\mathcal{Q}_n(v)) = \mathcal{J}(v) \quad (20)$$

Proof: Let $v \in V_R$, $u = u(x, t; v)$, $\mathcal{Q}_n(v) = [v]_n$, and $[u([v]_n)]_n$ be the corresponding discrete state vector. In theorem 8, it is proved that $\{\hat{u}^\tau\} \rightarrow u$ weakly in $W_2^{1,1}(\Omega)$.

$$\hat{u}^\tau(0, t) \rightarrow u(0, t), \quad \hat{u}^\tau(s(t), t) \rightarrow u(s(t), t) \text{ in } L_2[0, T]$$

We now show $\{u^\tau(0, t)\}$, $\{u^\tau(s(t), t)\}$ converge strongly in $L_2[0, T]$. It is enough to show that $\{u^\tau\}$ and $\{\hat{u}^\tau\}$ are equivalent in the strong topology of $W_2^{1,0}(\Omega)$. In theorem 8, it is proved that they are equivalent in the strong topology of $L_2(D)$. It remains to show that $\{u_x^\tau\}$ and $\{\hat{u}_x^\tau\}$ are equivalent in the strong topology of $L_2(\Omega)$.

Proof of Convergence Theorem

Proof of Lemma 11, cont'd

$$\|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Omega)}^2 \leq \frac{1}{3} \sum_{k=1}^n \tau^3 \int_0^{\min(s_{k-1}; s_k)} \left(\frac{d\tilde{u}(x; k)}{dx} \right)_{\bar{t}}^2 dx + \|u_x^\tau - \hat{u}_x^\tau\|_{L_2(\Gamma_n)}^2$$

where $s_k = s^n(t_k)$, s_n is the first component of $P_n([v]_n)$ and

$$\Gamma_n = \bigcup_{k=1}^n \{t_{k-1} < t \leq t_k; \min(s_{k-1}; s_k) < x < s(t)\}$$

Since s^n converges uniformly on $[0, T]$, $|\Gamma_n| \rightarrow 0$. By theorems 5 and 8, the integrand is uniformly bounded, and hence the second term on the RHS $\rightarrow 0$. The stability estimation implies the first term on the RHS $\rightarrow 0$, and hence $\{u_x^\tau\}$ $\{\hat{u}_x^\tau\}$ are equivalent in $L_2(\Omega)$.

Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Let $\nu^\tau(t) = \nu^k$, $\mu^\tau(t) = \mu^k$ if $t_{k-1} < t \leq t_k$, $k = 1, \dots, n$.

$$\|\nu^k - \nu\|_{L_2[0,T]} \rightarrow 0, \quad \|\mu^k - \mu\|_{L_2[0,T]} \rightarrow 0 \text{ as } \tau \rightarrow 0$$

Estimate the first term in $\mathcal{I}_n(Q_n(v))$ as

$$\begin{aligned} \beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 &= \beta_0 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(0; k) - \nu^k|^2 dt \\ &= \beta_0 \int_0^T |u^\tau(0, t) - \nu^\tau|^2 dt \end{aligned}$$

$$\lim_{n \rightarrow \infty} \beta_0 \tau \sum_{k=1}^n |u(0; k) - \nu^k|^2 = \beta_0 \|u(0, t) - \nu(t)\|_{L_2[0,T]}^2$$

Proof of Convergence Theorem

Proof of Lemma 11, cont'd

Estimate the second term in $\mathcal{I}_n(Q_n(v))$ as

$$\begin{aligned} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 &= 2\beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} (u^\tau(s(t), t) - \mu^\tau(t)) dx dt + \\ &+ \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} |u(s(t); k) - \mu^k|^2 dt + \beta_1 \sum_{k=1}^n \int_{t_{k-1}}^{t_k} \left(\int_{s(t)}^{s_k} \frac{\partial u^\tau}{\partial x} dx \right)^2 dt \end{aligned}$$

Set the three integrals on the RHS as I_1 , I_2 , and I_3 .

$$\lim_{n \rightarrow \infty} I_2 = \beta_1 \int_0^T |u^\tau(s(t), t) - \mu^\tau(t)|^2 dt = \beta_1 \int_0^T |u(s(t), t) - \mu(t)|^2 dt$$

Since $\|(u^\tau)_x\|_{L_2(D)}$ and $\|u^\tau(s(t), t) - \mu^\tau\|_{L_2[0, T]}$ are unif. bounded and $\{s^n\}$ converges uniformly to s on $[0, T]$,

$$\lim_{n \rightarrow \infty} I_1 = 0, \quad \lim_{n \rightarrow \infty} I_3 = 0$$

Proof of Convergence Theorem

Lemma 12

Hence

$$\lim_{\tau \rightarrow 0} \beta_1 \tau \sum_{k=1}^n |u(s_k; k) - \mu^k|^2 = \beta_1 \int_0^T |u(s(t), t) - \mu(t)|^2 dt$$

Lemma is proved.

Lemma 12

For arbitrary $[v]_n \in V_R^n$

$$\lim_{n \rightarrow \infty} \left(\mathcal{J}(\mathcal{P}_n([v]_n)) - \mathcal{I}_n([v]_n) \right) = 0 \quad (21)$$