

Optimal Control and Inverse Problems for PDEs.

I. Inverse Stefan Problem

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FIT Colloquium

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Introduction

One-phase Stefan problem: find the temperature function $u(x, t)$ in
 $\Omega = \{(x, t) : 0 < x < s(t), 0 < t \leq T\}$ and the free boundary $x = s(t)$
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Optimal Control Problem

$$\mathcal{J}(v) = \beta_0 \|u(0, t) - \nu(t)\|_{L_2[0, T]}^2 + \beta_1 \|u(s(t), t) - \mu(t)\|_{L_2[0, T]}^2 \quad (8)$$

$$V_R = \left\{ v = (s, g) \in W_2^2[0, T] \times W_2^1[0, T] : \delta \leq s(t) \leq l, \right. \\ \left. s(0) = s_0, \max(\|s\|_{W_2^2}; \|g\|_{W_2^1}) \leq R \right\}$$

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$$\Omega = \{(x, t) : 0 < x < s(t), 0 < t \leq T\}$$

$W_2^{1,1}(\Omega)$ -solution of the Neumann Problem

Definition 1

The function $u \in W_2^{1,1}(\Omega)$ is called a weak solution of the problem (9)-(12) if $u(x, 0) = \phi(x) \in W_2^1[0, s_0]$ and

$$\begin{aligned} 0 &= \int_0^T \int_0^{s(t)} [au_x \Phi_x - bu_x \Phi - cu \Phi + u_t \Phi + f \Phi] dx dt \\ &+ \int_0^T [\gamma(s(t), t)s'(t) - \chi(s(t), t)] \Phi(s(t), t) dt + \int_0^T g(t) \Phi(0, t) dt \quad (13) \end{aligned}$$

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$W_2^{1,1}(\Omega)$ – Hilbert space of all elements of $L_2(\Omega)$ whose weak derivatives $\frac{\partial u}{\partial x}, \frac{\partial u}{\partial t}$ belong to $L_2(\Omega)$, and scalar product is defined as

$$(u, v) = \int_{\Omega} \left(uv + \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial t} \frac{\partial v}{\partial t} \right) dx dt$$

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Formulated optimal control problem will be called Problem \mathcal{I} .

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$$\|[s]_n\|_{w_2^2}^2 = \sum_{k=0}^{n-1} \tau s_k^2 + \sum_{k=1}^n \tau s_{\bar{t},k}^2 + \sum_{k=1}^{n-1} \tau s_{\bar{t}\bar{t},k}^2, \quad \|[g]_n\|_{w_2^1}^2 = \sum_{k=0}^{n-1} \tau g_k^2 + \sum_{k=1}^n \tau g_{\bar{t},k}^2.$$

$$s_{\bar{t},k} = \frac{s_k - s_{k-1}}{\tau}, \quad s_{t,k} = \frac{s_{k+1} - s_k}{\tau}, \quad s_{\bar{t}\bar{t},k} = \frac{s_{k+1} - 2s_k + s_{k-1}}{\tau^2}.$$

Approximation and Interpolation Mappings

Introduce two mappings \mathcal{Q}_n and \mathcal{P}_n between continuous and discrete control sets:

$$\mathcal{Q}_n(v) = [v]_n = ([s]_n, [g]_n), \quad \text{for } v \in V_R$$

where $s_k = s(t_k)$, $g_k = g(t_k)$, $k = 0, 1, \dots, n$.

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$$\mathcal{P}_n([v]_n) = v^n = (s^n, g^n) \in W_2^2[0, T] \times W_2^1[0, T] \quad \text{for } [v]_n \in V_R^n,$$

$$s^n(t) = \begin{cases} s_0 + \frac{t^2}{2\tau} s_{\bar{t},1} & 0 \leq t \leq \tau, \\ s_{k-1} + (t - t_{k-1} - \frac{\tau}{2}) s_{\bar{t},k-1} + \frac{1}{2}(t - t_{k-1})^2 s_{\bar{t}t,k-1} & t_{k-1} \leq t \leq t_k. \end{cases}$$

$$g^n(t) = g_{k-1} + \frac{g_k - g_{k-1}}{\tau} (t - t_{k-1}), \quad t_{k-1} \leq t \leq t_k, k = \overline{1, n}.$$

Steklov Averages

$$d_k(x) = \frac{1}{\tau} \int_{t_{k-1}}^{t_k} d(x, t) dt, \quad h_k = \frac{1}{\tau} \int_{t_{k-1}}^{t_k} h(t) dt,$$

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Given $v = (s, g) \in V_R$ define Steklov averages of traces

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Discrete State Vector

Definition 3

$[u([v]_n)]_n = (u(x; 0), u(x; 1), \dots, u(x; n))$ is called discrete state vector if

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3. $u(x; k) \in W_2^1[0, s_k]$ iteratively continued to $[0, l]$ as

$$u(x; k) = u(2^n s_k - x; k), \quad 2^{n-1} s_k \leq x \leq 2^n s_k, \quad n = \overline{1, n_k},$$

$$n_k \leq N = 1 + \log_2 \left[\frac{l}{\delta} \right] \quad (16)$$

Discrete Optimal Control Problem

$$\mathcal{I}_n([v]_n) = \beta_0 \tau \sum_{k=1}^n \left(u(0; k) - \nu_k \right)^2 + \beta_1 \tau \sum_{k=1}^n \left(u(s_k; k) - \mu_k \right)^2 \quad (17)$$

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Formulated discrete optimal control problem will be called Problem \mathcal{I}_n .

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$$u^\tau(x, t) = u(x; k), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n},$$

$$\hat{u}^\tau(x, t) = u(x; k-1) + u_t(x; k)(t - t_{k-1}), \quad \text{if } t_{k-1} < t \leq t_k, \quad 0 \leq x \leq l, \quad k = \overline{1, n}$$

$$\hat{u}^\tau(x, t) = u(x; n), \quad \text{if } t \geq T, \quad 0 \leq x \leq l.$$

$$u^\tau \in V_2(D), \quad \hat{u}^\tau \in W_2^{1,1}(D)$$

Existence of the Optimal Control

$$D = \{(x, t) : 0 < x < l, 0 < t \leq T\}$$

$$a, b, c \in L_\infty(D), f \in L_2(D),$$

$$\phi \in W_2^1[0, s_0], \gamma, \chi \in W_2^{1,1}(D), \mu, \nu \in L_2[0, T],$$

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Theorem 4

The Problem \mathcal{I} has a solution, i.e.

$$V_* = \{v \in V_R : \mathcal{J}(v) = \mathcal{J}_* \equiv \inf_{v \in V_R} \mathcal{J}(v)\} \neq \emptyset$$

Convergence Theorem

Theorem 5

Sequence of discrete optimal control problems \mathcal{I}_n approximates the optimal control problem \mathcal{I} with respect to functional, i.e.

$$\lim_{n \rightarrow +\infty} I_{n_*} = J_*, \quad (19)$$

where

$$I_{n_*} = \inf_{V_R^n} I_n([v]_n), \quad n = 1, 2, \dots$$

If $[v]_{n_\epsilon} \in V_R^n$ is chosen such that

$$I_{n_*} \leq I_n([v]_{n_\epsilon}) \leq I_{n_*} + \epsilon_n, \quad \epsilon_n \downarrow 0,$$

then the sequence $v_n = (s_n, g_n) = \mathcal{P}_n([v]_{n_\epsilon})$ converges to some element $v_* = (s_*, g_*) \in V_*$ weakly in $W_2^2[0, T] \times W_2^1[0, T]$, and strongly in $W_2^1[0, T] \times L_2[0, T]$. In particular s_n converges to s_* uniformly on $[0, T]$. Moreover, piecewise linear interpolation \hat{u}^τ of the discrete state vector $[u[v]_{n_\epsilon}]_n$ converges to the solution $u(x, t; v_*) \in W_2^{1,1}(\Omega_*)$ of the Neumann problem (1)-(4) weakly in $W_2^{1,1}(\Omega_*)$.

Preliminary Results

Lemma 6

For sufficiently small time step τ , there exists a unique discrete state vector $[u([v]_n)]_n$ for arbitrary discrete control vector $[v]_n \in V_R^n$.

The *Proof* uses a Sobolev energy estimate and Galerkin method.

1) *Uniqueness:* Assume

$$u(x; k-1) \equiv 0, \quad f_k(x) \equiv 0, \quad (\gamma_{s^n}(s^n)')^k = \chi_{s^n}^k = g_k^n = 0$$

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$$\int_0^{s_k} \left[a_k(x) \left(\frac{du}{dx} \right)^2 - b_k \frac{du}{dx} u - c_k u^2 + \frac{1}{\tau} u^2 \right] dx = 0$$

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Preliminary Results

$$\epsilon = a_0/M \Rightarrow$$

$$\frac{a_0}{2} \int_0^{s_k} \left(\frac{du}{dx} \right)^2 dx + \left(\frac{1}{\tau} - \frac{1}{\tau_0} \right) \int_0^{s_k} u^2 dx \leq 0, \quad \tau_0 = \left(\frac{M^2}{2a_0} + M \right)^{-1}$$

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Corresponding homogeneous system:

$$\sum_{j=1}^N d_j \int_0^{s_k} \left[a_k(x) \psi'_j(x) \psi'_i(x) - b_k(x) \psi'_j(x) \psi_i(x) - c_k(x) \psi_j(x) \psi_i(x) + \frac{1}{\tau} \psi_j(x) \psi_i(x) + f_k(x) \psi_i(x) \right] dx = 0, \quad i = 1, \dots, N$$

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Multiply by d_i and add to derive

$$\int_0^{s_k} \left[a_k(x) \left(\frac{du_N}{dx} \right)^2 - b_k(x) \frac{du_N}{dx} u_N(x) - c_k(x) u_N^2(x) + \frac{1}{\tau} u_N^2(x) \right] dx = 0, \quad i = 1, \dots, N$$

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In a similar way to the uniqueness result, it follows that $u_N \equiv 0$, which implies the unique solution $u_N(x)$ to the original system.

Preliminary Results

We now seek a uniform estimation of sequence $\{u_N(x)\}$ in order to pass $N \rightarrow \infty$ and find the corresponding discrete state vector.

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Estimate the integrals on the LHS and estimate as before to find

$$\begin{aligned} & \frac{a_0}{2} \int_0^{s_k} \left(\frac{du_N}{dx} \right)^2 + \frac{1}{2\tau} \int_0^{s_k} u_N^2(x) \leq \left| (\gamma_{s^n}(s^n)')^k \right| + |\chi_{s^n}^k| |u_N(s_k)| + \\ & \quad + |g^k| |u_N(0)| + \frac{1}{\tau} \int_0^{s_k} \left[|f_k(x)| + \frac{1}{\tau} |u(x; k-1)| \right] |u_N(x)| dx \\ & \tau \leq \frac{\tau_0}{2}. \end{aligned}$$

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$\tau \leq \frac{\tau_0}{2}$. Morrey's inequality implies

$$\max\{|u_N(0)|; |u_N(s_k)|\} \leq \|u_N\|_{C[0, s_k]} \leq C \|u_N\|_{W_2^1[0, s_k]}$$

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Using Cauchy inequality with ϵ , it follows that

$$\begin{aligned}\|u_N\|_{W_2^1[0,s_k]}^2 \leq C & \left(\|u(x; k-1)\|_{L_2[0,s_k]}^2 + \|f_k\|_{L_2[0,s_k]}^2 + \right. \\ & \left. + \left| (\gamma_{s^n}(s^n)')^k \right|^2 + |\chi_{s^n}^k|^2 + |g^k|^2 \right)\end{aligned}$$

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That is, v satisfies the appropriate integral identity with $\eta(x) = \psi_i(x)$. Since $\{\psi_i\}$ is fundamental in $W_2^1[0, s_k]$, it follows that $v(x)$ satisfies the integral identity for any $\eta(x) \in W_2^1[0, s_k]$. By uniqueness, $u_N(x) \rightarrow v(x)$ weakly in $W_2^1[0, s_k]$. Lemma is proved.

Preliminary Results

Lemma 7

For arbitrary sufficiently small $\epsilon > 0$ there exists n_ϵ such that

$$Q_n(v) \in V_R^n, \quad \text{for all } v \in V_{R-\epsilon} \quad \text{and } n > n_\epsilon. \quad (20)$$

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$$Q_n(v) \in V_R^n, \quad \text{for all } v \in V_{R-\epsilon} \quad \text{and } n > n_\epsilon. \quad (20)$$

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The *Proof* follows from calculation of the corresponding norms.

1) Let $0 < \epsilon \ll R$, $v \in V_{R-\epsilon}$, $Q(b) = [v]_n = ([s]_n, [g]_n)$.

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By absolute continuity of the integral, it follows that

$$\lim_{\tau \rightarrow 0} \|s\|_{W_2^2[0,T]} = 0$$

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Corollary 8

Let either $[v]_n \in V_R^n$ or $[v]_n = Q_n(v)$ for $v \in V_R$. Then

$$|s_k - s_{k-1}| \leq C\tau, \quad k = 1, 2, \dots, n \tag{22}$$

where C is independent of n .

The *Proof* depends on the previous lemma and Morrey's inequality:

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Hence, for the first component of $[v]_n = Q_n(v)$,

$$[s]_n = (s(0), s(\tau), \dots, s(T))$$

we have

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we have

$$|s_k - s_{k-1}| \leq \|s'\|_{C[0,T]} |t_k - t_{k-1}| \leq C\tau$$

2. If $[v]_n \in V_R^n$, then $v^n = P_n([v]_n) \in V_{R+1}$ for n large enough, and $\|(s^n)'\|_{C[0,T]} \leq C_1 R$ by the previous result.

Since

$$s^n(0) = s_0, \quad s^n(t_k) = \frac{s_k + s_{k-1}}{2}, \quad k = 1, \dots, n$$

we have again

$$|s_k - s_{k-1}| \leq C\tau$$

Lemma 9

(Tikhonov, Vasil'ev 1980) Sequence I_n approximates the continuous optimal control problem I if and only if the following conditions are satisfied:

1. For arbitrary sufficiently small $\epsilon > 0$ there exists a number $N_1 = N_1(\epsilon)$ such that $\mathcal{Q}_N(v) \in V_R^n$ for all $v \in V_{R-\epsilon}$ and $N \geq N_1$; and for any fixed $\epsilon > 0$ and for all $v \in V_{R-\epsilon}$ the following inequality is satisfied:

$$\limsup_{N \rightarrow \infty} (I_N(\mathcal{Q}_N(v)) - J(v)) \leq 0. \quad (23)$$

2. For arbitrary sufficiently small $\epsilon > 0$ there exists a number $N_2 = N_2(\epsilon)$ such that $\mathcal{P}_N([v]_N) \in V_{R+\epsilon}$ for all $[v]_N \in V_R^N$ and $N \geq N_2$; and for all $[v]_N \in V_R^N$, $N \geq 1$ the following inequality is satisfied:

$$\limsup_{N \rightarrow \infty} (J(\mathcal{P}_N([v]_N)) - I_N([v]_N)) \leq 0. \quad (24)$$

3. $\limsup_{\epsilon \rightarrow 0} J_*(\epsilon) \geq J_*$, $\liminf_{\epsilon \rightarrow 0} J_*(-\epsilon) \leq J_*$, where

$$J_*(\pm \epsilon) = \inf_{V_{R \pm \epsilon}} J(u)$$

First Energy Estimate and its Consequences

Theorem 10

For all sufficiently small τ discrete state vector $[u([v]_n)]_n$ satisfies:

$$\begin{aligned} & \max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=1}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx \leq \\ & C \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ & \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (25) \end{aligned}$$

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$$\begin{aligned} & \max_{0 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau^2 \sum_{k=1}^n \int_0^l u_{\bar{t}}^2(x; k) dx \leq \\ & C \left(\|\phi\|_{W_2^1(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ & \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (26) \end{aligned}$$

Lemma 11

For all sufficiently small τ , discrete state vector $[u([v]_n)]_n$ satisfies the following estimation:

$$\begin{aligned} \max_{1 \leq k \leq n} \int_0^{s_k} u^2(x; k) dx + \tau \sum_{k=1}^n \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau^2 \sum_{k=1}^n \int_0^{s_k} u_t^2(x; k) dx \leq \\ C \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right), \quad (27) \end{aligned}$$

where C is independent of τ .

Proof. Choose $\eta(x) = 2\tau u(x; k)$ in (15) and use the equality

$$2\tau u_{\bar{t}}(x; k)u(x; k) = u^2(x; k) - u^2(x; k-1) + \tau^2 u_{\bar{t}}^2(x; k)$$

$$\begin{aligned} & \int_0^{s_k} u^2(x; k)dx - \int_0^{s_k} u^2(x; k-1)dx + \tau^2 \int_0^{s_k} u_{\bar{t}}^2(x; k)dx + \\ & 2\tau \int_0^{s_k} a_k(x) \left| \frac{du(x; k)}{dx} \right|^2 dx = 2\tau \int_0^{s_k} \left[b_k(x) \frac{du(x; k)}{dx} u(x; k) + c_k(x) u^2(x; k) - \right. \\ & \left. f_k(x) u(x; k) \right] dx - 2\tau \left[(\gamma_{s^n}(s^n)')^k - \chi_{s^n}^k \right] u(s_k; k) - 2\tau g_k^n u(0; k). \quad (28) \end{aligned}$$

Proof. Choose $\eta(x) = 2\tau u(x; k)$ in (15) and use the equality

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$$\begin{aligned} & \int_0^{s_k} u^2(x; k)dx - \int_0^{s_k} u^2(x; k-1)dx + a_0 \tau \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \\ & \tau^2 \int_0^{s_k} u_{\bar{t}}^2(x; k)dx \leq C_1 \tau \left[|(\gamma_{s^n}(s^n)')^k|^2 + |\chi_{s^n}^k|^2 + |g_k^n|^2 + \right. \\ & \left. \int_0^{s_k} f_k^2(x)dx + \int_0^{s_k} u^2(x; k)dx \right], \quad (29) \end{aligned}$$

$$\begin{aligned}
& (1 - C_1 \tau) \int_0^{s_k} u^2(x; k) dx \leq \int_0^{s_{k-1}} u^2(x; k-1) dx + \mathbf{1}_+(s_k - s_{k-1}) \times \\
& \int_{s_{k-1}}^{s_k} u^2(x; k-1) dx + C_1 \tau \left[|(\gamma_{s^n}(s^n)')^k|^2 + |\chi_{s^n}^k|^2 + |g_k^n|^2 + \int_0^{s_k} f_k^2(x) dx \right],
\end{aligned} \tag{30}$$

$$\begin{aligned}
(1 - C_1 \tau) \int_0^{s_k} u^2(x; k) dx &\leq \int_0^{s_{k-1}} u^2(x; k-1) dx + \mathbf{1}_+(s_k - s_{k-1}) \times \\
\int_{s_{k-1}}^{s_k} u^2(x; k-1) dx + C_1 \tau \left[|(\gamma_{s^n}(s^n)')^k|^2 + |\chi_{s^n}^k|^2 + |g_k^n|^2 + \int_0^{s_k} f_k^2(x) dx \right],
\end{aligned} \tag{30}$$

By induction

$$\begin{aligned}
\int_0^{s_k} u^2(x; k) dx &\leq (1 - C_1 \tau)^{-k} \int_0^{s_0} \phi^2(x) dx + \sum_{j=1}^k (1 - C_1 \tau)^{-k+j-1} \Big\{ C_1 \tau \times \\
&\quad \left[|(\gamma_{s^n}(s^n)')^j|^2 + |\chi_{s^n}^j|^2 + |g_j^n|^2 + \int_0^{s_j} f_j^2 dx \right] + \\
&\quad + \mathbf{1}_+(s_j - s_{j-1}) \int_{s_{j-1}}^{s_j} u^2(x; j-1) dx \Big\}.
\end{aligned} \tag{31}$$

$$(1 - C_1\tau) \int_0^{s_k} u^2(x; k) dx \leq \int_0^{s_{k-1}} u^2(x; k-1) dx + \mathbf{1}_+(s_k - s_{k-1}) \times \\ \int_{s_{k-1}}^{s_k} u^2(x; k-1) dx + C_1\tau \left[|(\gamma_{s^n}(s^n)')^k|^2 + |\chi_{s^n}^k|^2 + |g_k^n|^2 + \int_0^{s_k} f_k^2(x) dx \right], \quad (30)$$

By induction

$$\int_0^{s_k} u^2(x; k) dx \leq (1 - C_1\tau)^{-k} \int_0^{s_0} \phi^2(x) dx + \sum_{j=1}^k (1 - C_1\tau)^{-k+j-1} \left\{ C_1\tau \times \right. \\ \left[|(\gamma_{s^n}(s^n)')^j|^2 + |\chi_{s^n}^j|^2 + |g_j^n|^2 + \int_0^{s_j} f_j^2 dx \right] + \\ \left. + \mathbf{1}_+(s_j - s_{j-1}) \int_{s_{j-1}}^{s_j} u^2(x; j-1) dx \right\}. \quad (31)$$

For arbitrary $1 \leq j \leq k \leq n$ we have

$$(1 - C_1\tau)^{-k+j-1} \leq (1 - C_1\tau)^{-k} \leq (1 - C_1\tau)^{-n} = \left(1 - \frac{C_1 T}{n}\right)^{-n} \rightarrow e^{C_1 T}, \quad (32)$$

as $\tau \rightarrow 0$. Accordingly for sufficiently small τ we have

$$(1 - C_1\tau)^{-k+j-1} \leq 2e^{C_1 T} \quad \text{for } 1 \leq j \leq k \leq n \quad (33)$$

By applying CBS inequality from (31)-(33) it follows that

$$\begin{aligned} \max_{1 \leq k \leq n} \int_0^{s_k} u^2(x; k) dx &\leq C_2 \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \right. \\ &\quad \left. \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right) \end{aligned} \tag{34}$$

By applying CBS inequality from (31)-(33) it follows that

$$\begin{aligned} \max_{1 \leq k \leq n} \int_0^{s_k} u^2(x; k) dx &\leq C_2 \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g^n\|_{L_2(0, T)}^2 + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \right. \\ &\quad \left. \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx \right) \end{aligned} \quad (34)$$

Perform summation of (29) with respect to k from 1 to n and derive

$$\begin{aligned} \int_0^{s_n} u^2(x; n) dx + a_0 \tau \sum_{k=1}^n \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau^2 \sum_{k=1}^n \int_0^{s_k} u_{\bar{t}}^2(x; k) dx &\leq \\ 2\|\phi\|_{L_2(0, s_0)}^2 + C_1 \left(\|g^n\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma(s^n(t), t)(s^n)'(t)\|_{L_2(0, T)}^2 \right. \\ &\quad \left. + \|\chi(s^n(t), t)\|_{L_2(0, T)}^2 + \tau \sum_{k=1}^n \int_0^{s_k} u^2(x; k) dx \right) + \\ \sum_{k=1}^{n-1} \mathbf{1}_+(s_{k+1} - s_k) \int_{s_k}^{s_{k+1}} u^2(x; k) dx, \end{aligned} \quad (35)$$

From (34) and (35), (27) follows. Lemma is proved.

Extension Lemma

Lemma 12

Given discrete control vector $[v]_n \in V_R^n$, a discrete state vector $[u([v]_n)]_n$ satisfies the inequality

$$\begin{aligned} & \max_{1 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq \\ & C \left(\max_{1 \leq k \leq n} \int_0^{s_k} u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^{s_k} u_t^2(x; k) dx \right), \end{aligned} \tag{36}$$

where C is independent of τ .

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Given discrete control vector $[v]_n \in V_R^n$, a discrete state vector $[u([v]_n)]_n$ satisfies the inequality

$$\begin{aligned} & \max_{1 \leq k \leq n} \int_0^l u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^l u_t^2(x; k) dx \leq \\ & C \left(\max_{1 \leq k \leq n} \int_0^{s_k} u^2(x; k) dx + \tau \sum_{k=0}^n \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \tau \sum_{k=1}^n \int_0^{s_k} u_t^2(x; k) dx \right), \end{aligned} \tag{36}$$

where C is independent of τ .

Proof. By induction it follows that the first two terms on the left hand side are estimated by the first two terms on the right hand side with the constant $C = 2^N$, where N is defined in (16).

$$\tilde{u}(y; 0) = \phi(ys_0), \quad \tilde{u}(y; k) = u(ys_k; k), \quad 0 \leq y \leq 1, k = 1, \dots, n.$$

$$\tilde{u}(y; k) = \tilde{u}(2^n - y; k), \quad \text{for } 2^{n-1} \leq y \leq 2^n.$$

$$\begin{aligned}
& \sum_{k=1}^n \tau \int_0^l u_t^2(x; k) dx \leq \sum_{k=1}^n \tau \int_0^{2^N s_k} u_t^2(x; k) dx = \\
& \sum_{k=1}^n \tau \int_0^{2^N s_k} \left[\frac{\tilde{u}(x/s_k; k) - \tilde{u}(x/s_{k-1}; k-1)}{\tau} \right]^2 dx = \\
& \sum_{k=1}^n \tau s_k \int_0^{2^N} \left[\frac{\tilde{u}(y; k) - \tilde{u}(ys_k/s_{k-1}; k-1)}{\tau} \right]^2 dy \leq I_1 + I_2 \tag{37}
\end{aligned}$$

$$\begin{aligned}
I_1 &= 2 \sum_{k=1}^n \tau s_k \int_0^{2^N} \left[\frac{\tilde{u}(y; k) - \tilde{u}(y; k-1)}{\tau} \right]^2 dy = \dots = 2^{N+1} \sum_{k=1}^n \tau s_k \times \\
&\int_0^1 \tilde{u}_t^2(y; k) dy = 2^{N+1} \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx \leq 2^{N+2} \times \\
&\sum_{k=1}^n \tau \int_0^{s_k} u_t^2(x; k) dx + 2^{N+2} \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k-1) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx
\end{aligned} \tag{38}$$

$$\begin{aligned}
I_1 &= 2 \sum_{k=1}^n \tau s_k \int_0^{2^N} \left[\frac{\tilde{u}(y; k) - \tilde{u}(y; k-1)}{\tau} \right]^2 dy = \dots = 2^{N+1} \sum_{k=1}^n \tau s_k \times \\
&\int_0^1 \tilde{u}_t^2(y; k) dy = 2^{N+1} \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx \leq 2^{N+2} \times \\
&\sum_{k=1}^n \tau \int_0^{s_k} u_t^2(x; k) dx + 2^{N+2} \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k-1) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx
\end{aligned} \tag{38}$$

$$I_2 = 2 \sum_{k=1}^n \tau s_k \int_0^{2^N} \left[\frac{\tilde{u}(y; k-1) - \tilde{u}(ys_k/s_{k-1}; k-1)}{\tau} \right]^2 dy.$$

$$\begin{aligned}
& \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k-1) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx = \\
& \sum_{k=1}^n \frac{1}{\tau} \int_0^{s_k} \left| \int_{x \frac{s_{k-1}}{s_k}}^x \frac{du(\xi; k-1)}{d\xi} d\xi \right|^2 dx \leq \frac{C_1^2 l}{\delta} \sum_{k=0}^{n-1} \tau \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx,
\end{aligned} \tag{39}$$

$$\begin{aligned}
& \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k-1) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx = \\
& \sum_{k=1}^n \frac{1}{\tau} \int_0^{s_k} \left| \int_{x \frac{s_{k-1}}{s_k}}^x \frac{du(\xi; k-1)}{d\xi} d\xi \right|^2 dx \leq \frac{C_1^2 l}{\delta} \sum_{k=0}^{n-1} \tau \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx,
\end{aligned} \tag{39}$$

$$\begin{aligned}
I_2 & \leq \frac{2^{2N+1} C_1^2 N^2}{\delta} \sum_{k=1}^n \tau \int_0^{N2^N} \left| \frac{d\tilde{u}(x; k-1)}{dx} \right|^2 dx = \frac{2^{3N+1} C_1^2 N^3}{\delta} \times \\
& \sum_{k=0}^{n-1} \tau \int_0^1 \left| \frac{d\tilde{u}(x; k)}{dx} \right|^2 dx \leq \frac{2^{3N+1} C_1^2 N^3 l}{\delta} \sum_{k=0}^{n-1} \tau \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx
\end{aligned} \tag{40}$$

$$\begin{aligned}
& \sum_{k=1}^n \tau \int_0^{s_k} \left[\frac{u(x; k-1) - u(xs_{k-1}/s_k; k-1)}{\tau} \right]^2 dx = \\
& \sum_{k=1}^n \frac{1}{\tau} \int_0^{s_k} \left| \int_{x \frac{s_{k-1}}{s_k}}^x \frac{du(\xi; k-1)}{d\xi} d\xi \right|^2 dx \leq \frac{C_1^2 l}{\delta} \sum_{k=0}^{n-1} \tau \int_0^l \left| \frac{du(x; k)}{dx} \right|^2 dx,
\end{aligned} \tag{39}$$

$$\begin{aligned}
I_2 & \leq \frac{2^{2N+1} C_1^2 N^2}{\delta} \sum_{k=1}^n \tau \int_0^{N2^N} \left| \frac{d\tilde{u}(x; k-1)}{dx} \right|^2 dx = \frac{2^{3N+1} C_1^2 N^3}{\delta} \times \\
& \sum_{k=0}^{n-1} \tau \int_0^1 \left| \frac{d\tilde{u}(x; k)}{dx} \right|^2 dx \leq \frac{2^{3N+1} C_1^2 N^3 l}{\delta} \sum_{k=0}^{n-1} \tau \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx
\end{aligned} \tag{40}$$

$$\sum_{k=1}^n \tau \int_0^l u_t^2(x; k) dx \leq C \left(\sum_{k=0}^{n-1} \tau \int_0^{s_k} \left| \frac{du(x; k)}{dx} \right|^2 dx + \sum_{k=1}^n \tau \int_0^{s_k} u_t^2(x; k) dx \right)$$

(41)

Weak Compactness in $V_2^{1,0}$

Theorem 13

Let $[v]_n \in V_R^n, n = 1, 2, \dots$ be a sequence of discrete controls and the sequence $\{\mathcal{P}_n([v]_n)\}$ converges strongly in $W_2^1[0, T] \times L_2[0, T]$ to $v = (s, g)$. Then the sequence $\{u^\tau\}$ converges as $\tau \rightarrow 0$ weakly in $W_2^{1,0}(\Omega)$ to weak solution $u \in V_2^{1,0}(\Omega)$ of the problem (1)-(4), i.e. to the solution of the integral identity (14). Moreover, u satisfies the energy estimate

$$\|u\|_{V_2^{1,0}(D)}^2 \leq C \left(\|\phi\|_{L_2(0, s_0)}^2 + \|g\|_{L_2(0, T)}^2 + \|f\|_{L_2(D)}^2 + \|\gamma\|_{W_2^{1,0}(D)}^2 + \|\chi\|_{W_2^{1,0}(D)}^2 \right) \quad (42)$$

► U. G. Abdulla.

On the Optimal Control of the Free Boundary Problems for the Second Order Parabolic Equations. I. Well-posedness and Convergence of the Method of Lines.

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